

**REMARKS**

This Preliminary Amendment cancels without prejudice original claims 1-14 in the underlying PCT Application No. PCT/DE03/01717 and adds new claims 15-28. The new claims conform to U.S. Patent and Trademark Office rules and do not add new matter to the application.

In accordance with 37 C.F.R. § 1.125(b), the Substitute Specification (including the Abstract, but without the claims) contains no new matter. The amendments reflected in the Substitute Specification (including Abstract) are to conform the Specification and Abstract to U.S. Patent and Trademark Office rules or to correct informalities. As required by 37 C.F.R. § 1.121(b)(3)(ii) and § 1.125(c), a Marked Up Version Of The Substitute Specification comparing the Specification of record and the Substitute Specification also accompanies this Preliminary Amendment. Approval and entry of the Substitute Specification (including Abstract) are respectfully requested.

The underlying PCT Application No. PCT/DE03/01717 includes an International Search Report, dated October 15, 2003. The Search Report includes a list of documents that were uncovered in the underlying PCT Application.

Applicant asserts that the subject matter of the present application is new, non-obvious, and useful. Prompt consideration and allowance of the application are respectfully requested.

Respectfully Submitted,  
KENYON & KENYON

Dated: 3/24/05

By:   
Richard L. Mayer  
(Reg. No. 22,490)  
  
P. No.  
36,197)

One Broadway  
New York, NY 10004  
(212) 425-7200

CUSTOMER NO. 26646

10/529111

[10191/4083]

JC17 Rec'd PCT/PTO 24 MAR 2005

METHOD, CONTROL UNIT, AND COMPUTER PROGRAM FOR DETECTING DEFECTIVE PRESSURE SENSORS IN AN INTERNAL COMBUSTION ENGINE

Background InformationField of the Invention

The present invention relates to a method, a control unit, and a computer program for detecting a defective intake-manifold pressure sensor and/or a defective ambient-pressure sensor in an internal combustion engine.

Background Information

10 An intake-manifold pressure sensor is used, for example, to diagnose the exhaust-gas recirculation in an internal combustion engine and therefore supplies important information for a control unit to control the internal combustion engine. A load signal representing the current load of the internal 15 combustion engine, or the setting of a correct torque selected by the driver, may be derived from the pressure in the intake manifold. In addition, an optimum injection time in an internal combustion engine having throttle control may be ascertained from the load signal.

20 Because of the ~~described~~—high importance of the intake-manifold pressure sensor during the operation of an internal combustion engine, it is desirable for defects in the intake-manifold pressure sensor to be diagnosed early.

25 Diagnostic methods for detecting the defectiveness of intake-manifold pressure sensors are ~~already known from~~ in the related art, but only in the case of conventional gasoline engines, in particular spark-ignition engines. The conventional internal

combustion engines are distinguished in that their load control is implemented via the throttle valve, where there is a fixed relationship between the pressure in the intake manifold and the load, or between the throttle-valve angle and 5 the load.

An example of such a diagnostic method for conventional spark-ignition engines is known from described, e.g., in published German patent document DE 199 46 874 A1. Here, three different 10 signals L1, L2, and L3 are produced from different operating parameters, L1 representing the mass flow rate of air that flows into an intake manifold of the spark-ignition engine, L2 representing the pressure in the intake manifold, and L3 representing a fuel signal ascertained from the mass flow rate 15 of fuel. These signals are compared to each other in pairs and united to form combinations when variations occur. Different combinations of deviations are assigned different causes, i.e., different sources of error, for the deviations. Thus, e.g., in a first part of the method, it can initially be 20 deduced that, when a particular deviation is present, either the intake-manifold pressure sensor and/or the exhaust-gas recirculation valve is defective. In a further part of the method, it may then be determined more accurately if the intake-manifold pressure sensor or the exhaust valve is 25 defective. To this end, the pressure in the intake manifold during both the operation of the engine and its stoppage is measured and evaluated during the post-operation of the corresponding engine control unit. If the intake-manifold pressure is the same in both cases, it may be deduced that 30 there is a defect in the intake-manifold pressure sensor; however, if the pressure in the intake manifold while the engine is stopped is less than that when the engine is being operated, it may then be deduced that an exhaust-gas recirculation valve is defective.

In addition, ambient-pressure sensors for use in internal combustion engines are known in the related art. In addition to the intake-manifold pressure sensors, they also supply 5 important information for a control unit to control an internal combustion engine. Ambient-pressure sensors are used for, *inter alia*, ascertaining the maximum torque of the internal combustion engine. Diagnostic methods for ambient-pressure sensors are also known in the ~~related~~ art. In 10 conventional gasoline engines in which the load is controlled via the throttle valve, an ambient-pressure sensor can, however, only be checked for its correct method of functioning, *i.e.,* plausibility-checked, while starting or during full load, since in conventional gasoline engines, a 15 pressure that approaches ambient pressure is only present in the intake manifold under these conditions.

However, in internal combustion engines having variable valve timing, *i.e.,* in internal combustion engines having 20 throttleless load control, the load of the internal combustion engine is no longer controlled via the throttle valve and, therefore, via the pressure in the intake manifold, but rather via a change in its valve timing and/or its valve lift. The internal combustion engines having fully variable valve timing 25 are distinguished by a lower fuel consumption than conventional gasoline engines.

Fig. 3 schematically illustrates such an internal combustion engine 100 having variable valve timing. Internal combustion engine 100 includes an engine block 110 having a piston 112, which moves up and down in it. Connected to the engine block 30 is an intake manifold 120 having a built-in throttle valve 122 and an exhaust pipe 130. However, in contrast to conventional spark-ignition engines, throttle valve 122 is not used for

controlling load. The control of the air supply and air exhaust through the intake manifold and the exhaust pipe, and therefore the control of the load of the internal combustion engine, is carried out via valves 140, which are controlled by 5 a control unit 200, the control being implemented with the aid of fully variable timing edges. Instead of a single control unit 200, several control units interconnected by any communication link may also be used for controlling valves 140. The valves may be moved, for example, by electromagnetic 10 or electrohydraulic actuators.

Control unit 200 includes an ambient-pressure sensor 210 for supplying a throttle-valve pressure signal, which represents pressure  $p_{\text{before\_DK}}$  upstream from throttle valve 122. In this 15 context, ambient-pressure sensor 210 does not directly supply pressure  $p_{\text{before\_DK}}$ , but it primarily supplies only the ambient pressure, i.e., the air pressure upstream from air filter 150 of the internal combustion engine. Then, actual pressure  $p_{\text{before\_DK}}$  upstream from the throttle valve may be 20 subsequently derived in either ambient-pressure sensor 210 itself or control unit 200, by subtracting a pressure drop occurring in air filter 150 of the internal combustion engine from the measured ambient pressure.

25 In throttleless operation of the internal combustion engine, the pressure upstream from the throttle valve must be equal to the pressure in the intake manifold. An intake-manifold pressure sensor 220 is typically provided in the case of the control units of the related art. Intake-manifold pressure 30 sensor 220 provides an intake-manifold pressure signal, which represents pressure  $p_{\text{intake}}$  in intake manifold 120 of internal combustion engine 100. Sometimes, they are additionally provided with an ambient-pressure sensor 210.

However, as ~~just explained above~~, since the load control in internal combustion engines having fully variable valve timing is no longer implemented via the throttle valve, all of the already known diagnostic methods for pressure sensors, which 5 are based on deriving a load signal representing the load of the internal combustion engine from the angular position of the throttle valve or the pressure in the intake manifold, are no longer applicable to internal combustion engines having fully variable valve timing.

10

Therefore, ~~on the basis of the mentioned related art, the~~ an object of the present invention is to ~~further develop~~ provide a known method, a known control unit, and a known computer program for detecting a defective intake-manifold pressure 15 sensor and/or a defective ambient-pressure sensor in a conventional internal combustion engine in such a manner, that ~~this detection is also possible in internal combustion engines~~ having fully variable valve timing.

20 Summary

This object is achieved by the ~~method claimed in Claim 1, control unit, and program according to the present invention.~~ In contrast to the related art, the ~~claimed~~ present method 25 dispenses with deriving load signals from the position of the throttle valve or from the intake-manifold pressure for detecting if at least one of two pressure sensors, namely the intake-manifold pressure sensor or the ambient-pressure sensor, is defective. Instead, the method of the present 30 invention allows this detection to take place exclusively on the basis of a direct evaluation of the pressure upstream from the throttle valve and the pressure in the intake manifold.

According to a ~~preferred, advantageous refinement~~ an example embodiment, the claimed method includes further steps, in order to be able to determine which of the two pressure sensors is defective. To this end, the internal combustion engine having throttleless load control is artificially shifted into an operating state, which simulates throttled load control. In the scope of this simulation, it is also possible to then derive simulated load signals from both the pressure in the intake manifold and the angular position of the throttle valve. According to the present invention, the simulated load signals are used for identifying the pressure sensor that is actually defective.

~~The above mentioned object of the present invention is also achieved by the control unit claimed in Claim 6 and the computer program claimed in Claim 13.~~

~~The advantages of the control unit and the computer program essentially correspond to the above mentioned advantages with regard to the claimed method.~~

~~Further advantageous refinements of the claimed method, the control unit, and the computer program are subject matter of the dependent claims.~~

25 ~~Preferred exemplary embodiments of the present invention are subsequently explained in detail in light of the attached figures. The figures show: Brief Description of the Drawings~~

30 Fig. 1a shows an example embodiment of a method of the present invention for detecting defective pressure sensors in an internal combustion engine and a first logic module provided for implementing the method. Fig. 1a

Fig. 1b shows an example embodiment of a control unit of the present invention.

5 Fig. 2 shows another example embodiment A further refinement of the method according to the present invention and a second logic module provided for implementing the further refinement, and.

10 Fig. 3 shows a known conventional internal combustion engine having variable valve timing, and a corresponding, knownconventional control unit for controlling the valves.

#### Detailed Description

15 Fig. 1a illustrates a method for determining whether or not at least one of two pressure sensors, namely the intake-manifold pressure sensor and/or the ambient-pressure sensor, is defective in the case of an internal combustion engine having 20 variable valve timing ~~in accordance with as shown in~~ Fig. 3. The method ~~steps~~ according to illustrated in Fig. 1a ~~does do~~ not yet allow one to specifically determine which of the two pressure sensors is defective; such a determination may only be made with the aid of ~~the further refinement~~steps of the 25 method described below with reference to Fig. 2.

The method is illustrated in Fig. 1a by showing the functional layout of a first logic module 240 according to the present invention, which ~~is preferably~~may be a component of a control 30 unit 200 for controlling the valves of internal combustion engine 100, ~~see which control unit 200 is shown in~~ Fig. 1b. First logic module 240 allows the claimed method to be implemented. The layout of first logic module 240 is described

below in detail; the individual steps of the claimed method are may also automatically be deduced from this.

According to Fig. 1a, first logic module 240 receives both a  
5 throttle-valve pressure signal, which represents pressure  
p\_before\_DK, and an intake-manifold pressure signal, which  
represents pressure p\_intake in the intake manifold of the  
internal combustion engine; ~~in order to generate. Generation~~  
10 ~~of these signals: see is described below in connection with~~  
Fig. 3 and the corresponding part of the description.

According to the present invention, first logic module 240  
also receives a first status signal from a first operating-  
state detector 230, the first status signal indicating whether  
or not the internal combustion engine is being operated in a  
15 throttleless operating state. As an alternative, the status  
signal may also be generated by another logic module inside  
control unit 200.

As shown in Fig. 1a, logic module 240 includes a first  
20 subtraction unit 242 for calculating a pressure difference  
delta\_p by subtraction of the intake-manifold pressure signal  
from the throttle-valve pressure signal. This pressure  
difference is supplied to a first comparator unit 244, which  
determines if pressure difference delta\_p is greater than a  
25 first threshold value Delta\_P1. A first AND gate 246 ANDs the  
logical output signal of first comparator unit 244 and the  
first status signal. The output signal of this first AND gate  
246 makes a first statement as to whether or not one of  
the pressure sensors 210, 220 is defective; this is exactly the  
30 case, when pressure difference delta\_p is actually greater  
than first threshold value Delta\_P1 and internal combustion  
engine 100 is simultaneously being operated in a throttleless  
manner, as indicated by the first status signal. In this

context, first threshold value Delta\_P1 ~~is preferably~~may be set to approximately zero.

includes a second comparator unit 248 for determining if 5 pressure difference delta\_p is less than second threshold value Delta\_P2, where Delta\_P2 ~~is preferably~~may be zero. When this is the case, then, independently of the first statement, it is possible to make a second statement that one of the two pressure sensors 210, 220 is operating incorrectly. This 10 statement is physically based on the fact that the pressure in intake manifold 120 can never be greater than the pressure upstream from throttle valve 122.

First logic module 240 also includes an OR gate 249 for ORing 15 the output signal of first AND gate 246 and the output signal of second comparator unit 248. This OR operation is used for generating a first error signal E\_DS\_DSU, which represents an error in one of the two pressure sensors 210, 220, when such an error has already been detected at either the output of 20 first AND gate 246 or at the output of second comparator unit 248 or at both outputs.

Fig. 2 illustrates another example embodiment, which is a further refinement of the method represented in Fig. 1, this 25 further refinement being used to allow an exact determination as to whether the intake-manifold pressure sensor or ambient-pressure sensor 210 is defective. This further refinement is implemented in the form of a second logic module 250, which ~~is~~ may be assigned to control unit 200 as well, see as 30 shown in Fig. 1b.

According to Figures 1b and 2, second logic module 250 implements the above-mentioned further refinement of the method by logically combining first error signal ES\_DS\_DSU, a

first load signal `load_from_intake-manifold-pressure`, which represents the load of the internal combustion engine derived from the pressure in the intake manifold, and a second load signal `load_from_DK`, which represents the load of the internal combustion engine derived from the angular position of throttle valve 122.

To implement the further refinement of the method, an operating state that includes throttled load control is simulated in the internal combustion engine 100 having absolutely variable valve timing. To this end, valves 140 are preferably controlled by control unit 200, using fixed timing edges. This special operating state is represented by a second status signal `B_DK_occurred`, which is likewise supplied to second logic module 250 as an input variable.

Second logic module 250 includes a second subtraction unit 251 for calculating a load difference by subtraction of the second load signal from the first load signal, as shown in Fig. 2. An absolute-value generator 252 calculates the absolute value of the load difference before this is supplied to a third comparator unit 253. Third comparator unit 253 determines if the absolute value of the load difference is greater than a third threshold value `Delta_load`.

A second AND gate 254 ANDs first error signal `E_DS_DSU` and second status signal `B_DK_occurred`. The output signal of second AND gate 254 is transmitted, together with the output signal of third comparator unit 253, to a third AND gate 255, which means that the output signal of third AND gate 255 represents the result of ANDing the mentioned, inputted signals. In other words: the output signal of third AND gate 255 represents a second error signal `E_DS_intake`, i.e., it indicates, if applicable, the defectiveness of intake-manifold

pressure sensor 220. Such defectiveness is present, when the absolute value of the difference of the load of the internal combustion engine derived from the pressure in the intake manifold and the load derived from the angle of the throttle valve is greater than third threshold value  $\Delta_{load}$ , and when, in addition, the presence of a defect in at least one of the pressure sensors, ambient-pressure sensor 210 or intake-manifold pressure sensor 220, was simultaneously detected in the preliminary procedure described above with reference to Fig. 1a, and when an operation that includes throttled load control was simulated in internal combustion engine 100. The conclusion that the intake-manifold pressure sensor is defective is valid, since signal  $load\_from\_DK$  is reliably monitored by other diagnoses and is therefore correct.

Second logic module 250 further includes a fourth AND gate 256 for ANDing the output signal of comparator unit 253 inverted by an inverter 257 and the output signal of second AND gate 254, as shown in Fig. 2. The output signal of fourth AND gate 256 represents a third error signal  $E\_DS\_Umg$ , which indicates, if applicable, a defect in ambient-pressure sensor 210. Such a defect is present, when the absolute value of the difference of the load of the internal combustion engine derived from the pressure in the intake manifold and the load derived from the angular position of the throttle valve is less than or equal to third threshold value  $\Delta_{load}$ , and, at the same time, a defect in at least one of pressure sensors 210, 220 was already absolutely detected in the preliminary procedure described above with reference to Fig. 1, and an operation that includes throttled load control was simulated in the internal combustion engine.

Both the first and second logic modules may each be implemented independently of each other in the form of a hardware circuit.

5 ~~However, it is particularly important to implement the~~ The method of the present invention, and therefore ~~to~~ ~~implement also~~ the first and/or second logic module 240, 250, may be implemented in the form of a computer program. In this context, the computer program is executable on a computing 10 element, particularly e.g., on a microprocessor in control unit 200, and is suitable for carrying out the method of the present invention. In this case, the present invention is therefore implemented by the computer program, ~~so that this computer program represents the present invention in the same~~ 15 manner as the method, ~~for whose execution the computer program is suitable.~~ The computer program is ~~preferably~~ may be stored in a memory element. In particular, an electrical storage medium, e.g., a random-access memory (RAM), a read-only memory (ROM), or a flash memory, may be used as the memory element.

20

Abstract

ABSTRACT

The invention relates to a method, a control unit 200, and a computer program for detecting a defective intake-manifold pressure sensor 220 and/or a defective ambient-pressure sensor 210 in an internal combustion engine 100. The related art already describes diagnostic methods and devices for detecting the defectiveness of intake manifold pressure sensors, but only in conventional internal combustion engines in which the load is controlled via the throttle valve 122, and not for internal combustion engines 100 in which the load is controlled via the valve timing. Therefore, on the basis of this related art, the object of the present invention is to further develop a known method, a known control unit 200, and a known computer program for detecting a defective intake-manifold pressure sensor 220 and/or a defective ambient-pressure sensor 210 in a conventional internal combustion engine 100 in such a manner, that this detection is also possible in internal combustion engines 100 having a variable valve timing are provided. This object of the present invention is achieved in that the desired detection is carried out exclusively on the basis of a direct evaluation of the pressure upstream from the throttle valve 122 and the pressure in the intake manifold 120. This advantageously method eliminates the need for deriving load signals from these pressures, as is necessary in the related art, at least for the determination as to whether at least one of the pressure sensors is defective (Fig 1).